# Multi-channel(4 channel / 2 channel) modular type PID control

## Features

- Multi-channel(4 channel/ 2 channel) simultaneous controlling possible
- High-speed sampling cycle(4 channel : 100ms, 2 channel : 50ms)
- No communication and power supply for expansion modules required by using side connectors
   Max. 31 units (124 channels / 62 channels)
- Input channel isolated design(Dielectric strength 1,000 VAC)
- Heating/Cooling simultaneous controlling
- Allows parameter setting and monitoring by USB port of PC : only for using DAQMaster or USB to Serial converter (SCM-US, sold separately)
- Easy maintenance via connector type connection : Sensor input connector, control output connector, power/communication connector
- Multi input / Multi range
- Heater disconnection function(CT input)
- \* CT, sold separately : CSTC-E80LN, CSTC-E200LN



# User manual

- •Visit our website (www.autonics.com) to download user manual and communication manual.
- •User manual describes for specifications and function, and communication manual describes for RS485 communication (Modbus RTU protocol) and parameter address map data.

# Integrated device management program(DAQMaster)

•DAQMaster is a integrated device management program for convenient

management of parameters and multiple device data monitoring.

•Visit our website (www.autonics.com) to download user manual and integrated device management program

< Computer specification for using software >

Item	Recommended specification
Processor	IBM PC compatible computer with Intel Pentium III or above
Operating system	Windows 98 / NT / XP / Vista / 7
RAM	Over 256MB
Hard disk	Over 1GB of available space
VGA	Over 1024×768
Communication port	RS232 Serial port, USB port



# Ordering information

М	4 I	N 2	2 F	R B					
				Module type	В	Bas	sic module		
					E	Exp	ansion module		
					2 Channel	R	Relay output		
				Control output		С	Current or SSR output selectable		
					4 Channel	R	Relay output		
			Power	supply		S	SSR drive output		
			1 Ower	Supply	2	24VDC			
		Sub ou	tput		2 Channel	Alarm1+Alarm2 Relay output     Alarm1+Alarm2+Alarm3+Alarm4 Relay out			
					4 Channel	N None(XNo sub output)			
	Channel	l				2 Channel			
						4 Channel			
Item					ТМ	Mul	ti-channel modular temperature controller		

%Make sure to purchase both expansion module and basic module together because power supply/communication terminals are provided with basic modules only.



NEW

# Specifications

Spec	cification	IS												(A) Photo
Series		TM2- 22RB	TM2- 42RB	TM2- 22RE	TM2- 42RE	TM2- 22CB	TM2- 42CB	TM2- 22CE	TM2- 42CE	TM4- N2RB	TM4- N2RE	TM4- N2SB	TM4- N2SE	electric sensor
Channel		2 Chanr (Each cl	Channel Ach channel insulated-Dielectric strength 1,000 VAC) def channel insulated-Dielectric strength 1,000 VAC) def channel insulated-Dielectric strength 1,000 VAC)									(B) Fiber optic sensor		
Power Sup	olv	24VDC								Dielectri	c strengt	un 1,000 v	AC)	(C)
Allowable vo	,		110% of rated voltage									Door/Area sensor		
Power cons	<u> </u>		V(At maxi	0										1
Indicating ty			`		,	ng & monit	oring with	external	devices	(PC or PLC	C)			(D) Proximity
Input	RTD	DPt100	Ω, JPt100	Ω 3 wire	(Allowable	e line resis	stance : N	lax. 5Ω)			,			sensor
type	Thermocouple	K, J, E,	T, L, N, U	, R, S, B,	C, G, PLI	I(13types)	)	,						(E)
	RTD													Pressure sensor
Indicating	Thermocouple <sup>*1</sup>	(Bigger	one eithe	r PV ±0.5	% or ±1℃	C) ±1digit I	Max.							
accuracy	CT input	(+5% E	S.) ±1digi	t Max										(F) Rotary
	Current output		F.S.) ±1di											encoder
Influence of				-										(G)
Temperature	RTD					digit Max.(				it is ±5℃ at	-100°C b	elow.)		Connector/ Socket
×2	Thermocouple	•mermo	couples L	, U, C, G, I	К, З, В. (В		eimer PV ±	0.5% 01 ±0	(C) ± Taigi					
	Relay	250VAC	3A 1a			-				250VAC	3A 1a	<u> </u>		(H) Temp. controller
Control output	SSR	—				12VDC	±3V 30m/	A Max.		—		22VDC ± Max.	±3V30mA	controller
output	Current	—					mA or DO	C 0-20mA 00Ω Max	.)					(I) SSR/ Power
Sub output	Relay	250VAC	3A 1a							_				controller
Sub output	Communication	RS485 (	Communi	cation out	tput(Modb	ous RTU)								(J)
	CT input	0.0-50.0	A(Primar	y current	meaurem	ent range	) ※CT ra	itio = 1/10	00	-				Counter
Event input	Digital input	•Non-co	<ul> <li>Contact input: ON Max. 1kΩ, OFF Min. 100kΩ</li> <li>Non-contact input: ON Max. 1.5V residual voltage, OFF Max. 0.1mA leakage current</li> </ul>						-				(K) Timer	
Control	Heating, cooling		current : /			D control I	node							(L) Panel meter
method Hysteresis	Heating&cooling	1 to 100		to 100°C	/°F) variab					1 to 100	diait			(M)
Proportiona	l band (P)	0.1 to 99		10 100 0/	r) valiau	ne -				110100	uigit			Tacho/ Speed/ Pulse
Integral time		0 to 999												meter
Derivative t		0 to 999												(N) Display
Control peri				Only rela	v and SSI	R output ty	(ne)							unit
Manual res	,	0.0 to 10		only rela	y and oor	( output t	(pc)							(0)
Sampling p				synchrono	ous sampl	ina)				100ms(4 c	channel sv	nchronous	sampling)	Sensor controller
Dielectric st		· ·		,		en power	source te	rminal an	d input te	· · ·			camping)	
Vibration re									•		for 2 ho	ure		(P) Switching
Relay	Mechanical		0.75mm amplitude at frequency of 5 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours Min. 10,000,000 operations									power supply		
life cycle	Electrical		Min. 10,000 operations (250 VAC 3A resistance load)									(Q)		
Insulation re			at 500VD			ricolotai								Stepping motor&
Noise resist		,		00	,	ator (puls	e width 1	us) +0.5k\	/					Driver&Controller
Environ	Ambient	Square shaped noise by noise simulator (pulse width 1µs) ±0.5kV -10 to 50°C, storage: -20 to 60°C									(R) Graphic/ Logic panel			
-ment	Ambient	35 to 85	%RH, sto	orage: 35	to 85%RF	4								(S) Field
	······,	Expansi	on conne	ctor										network device
Accessory			Power / communication connector[%Basic module only]										1	
Insulation t	уре	Double i		or reinfor					ength bet	tween the r	measurin	ng input pa	art	(T) Software
Approval		<b>(€ ,9</b> )												
Unit weight	t	Approx. 144g	Approx. 152g	Approx. 135g	Approx. 143g	Approx. 139g	Approx. 148g	Approx. 130g	Approx. 139g	Approx. 174g	Approx. 166g	Approx. 160g	Approx. 152g	(U) Other
										- 1	-			

%1. In case of thermocouple K, T, N, J, E at -100°C below and L, U, PlatineIII, it is ±2°C ±1digit Max.

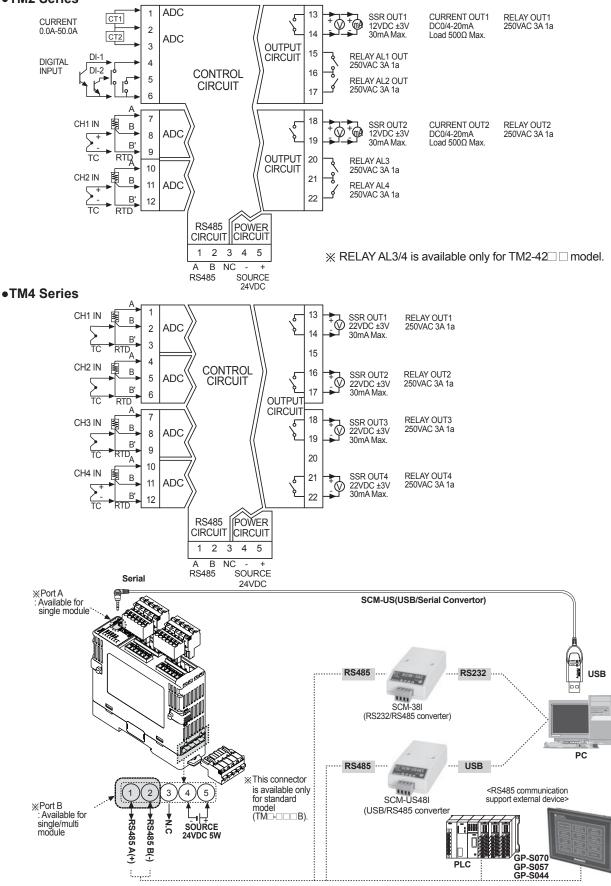
In case of thermocouple B, indicating accuracy cannot be ensured under 400°C. In case of thermocouple R, S at 200°C below and thermocouple C, G, it is 3°C ±1digit Max. %2. Applied when used out of range 23 ±5°C.

\*Environment resistance is rated at no freezing or condensation.

(A)

# Connections and block diagram

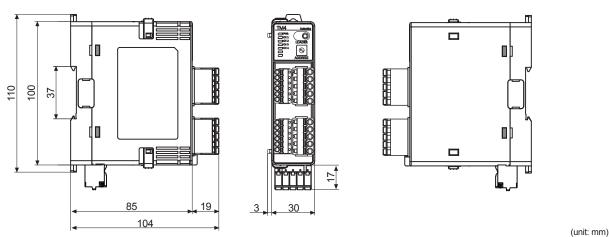
#### TM2 Series



**Autonics** 

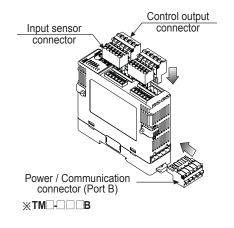
# **Multi-Channel Module type PID Control**

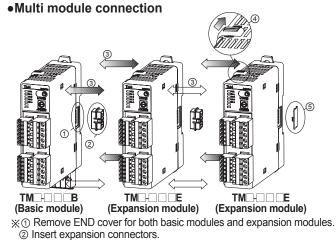
# Dimensions



# Installation

#### Connector connection

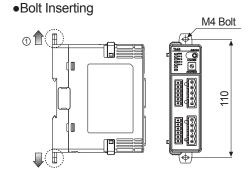




- Connect an expansion module without space.
- ④ Fix the LOCK switch by pushing it in the LOCK direction.
- Mount the END cover at each side.

\*Up to 30 expansion modules can be connected to a basic module. Use an adequate power supply system for the power input specifications and overall capacity.

[Maximum power (155W=31ea X 5W) is required when connecting 31 units]



① Pull each Rail Lock switch up and down.

M4 Bolt

Insert the bolts to fix.

(Tightening torque is 0.5N·m to 0.9N·m.)

(O) Sensor controller (P) Switching power supply

(A) Photo electric sensor

(B) Fiber

optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(Q) Stepping motor& Driver&Controller

(R) Graphic/ Logic panel

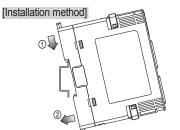
(S) Field

network device

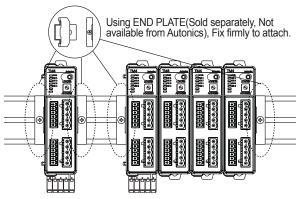
(T) Software

(U) Other

#### DIN Rail Installation



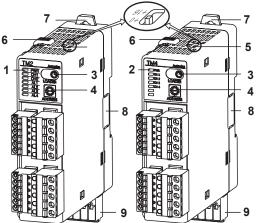
① Put the top edge of the rail Lock on the top edge or the DIN rail.
 ② Push the module body in while pressing down.



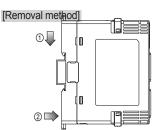
# Parts description

**©TM2 Series** 

**©TM4 Series** 



- 3. PC loader port(Port A)
- Integrated device management program (DAQMaster, free download on our site) is for setting parameter by PC through USB to Serial converter (SCM-US, sold separately).
   Communication address setting switch (SW1)
- : Used to set communication address group change switch 5. Communication address group change switch
- Communication address group change switch (SW2)
   When communication address is over 16
- : When communication address is over 16, select +16.
- Ex) For setting 20 address, set the communication address group change switch (SW) as +16 and set the communcation address setting switch (SW1) as 4.
- 6. Lock switch: Used for fixing units to DIN rail or to the wall7. Rail lock
- : Used for fixing units to DIN rail or to the wall 8. END cover
- : Remove it when connecting each module. 9. Power supply/Communications connector(Port B)
- : Only Basic module(TM\_-\_2\_B)



Press down the module body.
 Pull the module body forward.

#### $\ensuremath{\ll}\xspace$ Make sure to install the unit vertically to the ground.





Vertical Installation



(X)

#### 1. Indicating LED(TM2 Series)

Status			Alarm out					
$  \rangle$	Initial power on	Control	N.O		N.C		Auto	
Indi- cating LED	×1	a	OFF(OPEN)	FF(OPEN) ON(CLOSE)		ON(CLOSE)	tuning <sup>*2</sup>	
PWR LED ×3	Green	Green	-	-	-	-	Green	
CH1 LED	2400bps-Flashing	Power ON-RED	-	-	-	-	Flashing	
CH2 LED	4800bps-Flashing	Power ON-RED	-	-	-	-	Flashing	
AL1 LED	9600bps-Flashing	Power ON- YELLOW <sup>%4</sup>	Light OFF	Light ON	Light ON	Light OFF	Light OFF	
AL2 LED	19200bps-Flashing	Power ON- YELLOW <sup>×5</sup>	Light OFF	Light ON	Light ON	Light OFF	Light OFF	
AL3 LED	38400bps-Flashing	-	Light OFF	Light ON	Light ON	Light OFF	Light OFF	
AL4 LED	-	-	Light OFF	Light ON	Light ON	Light OFF	Light OFF	

#### 2. Indicating LED(TM4 Series)

	/		
Status Indicating LED	Initial power on <sup>×1</sup>	Control output	Auto tuning <sup>*2</sup>
PWR LED <sup>*3</sup>	Green	Green	Green
CH1 LED	2400bps- Flashing	ON - RED	Flashing
CH2 LED	4800bps- Flashing	ON - RED	Flashing
CH3 LED	9600bps- Flashing	ON - RED	Flashing
CH4 LED	19200bps- Flashing	ON - RED	Flashing
	38400bps- Flashing	-	-

%1. In case of initial power on, default communication speed will be flashing for 5 sec. (1 sec. cycle).

%2. Each CH3 LED will be flashing during auto tuning (1 sec. cycle).

※3. Power LED will be flashing while communicating with external units (1 sec. cycle).

※4. Light ON when control type for CH1 is heating & cooling type and cooling output is provided.

%5. Light ON when control type for CH2 is heating & cooling type and cooling output is provided.

### Input sensor type and temperature range

Input sensor	No.	Dot	Display	Input range(°C)	Input range(°F)	ele		
		0	1	K(CA).H	-200 to 1350	-328 to 2462	(B) Fil	
	K(CA)	1	0.1	K(CA).L	-200.0 to 1350.0	-328.0 to 2462.0	ор	
	1/10)	2	1	J(IC).H	-200 to 800	-328 to 1472	se	
	J(IC)	3	0.1	J(IC).L	-200.0 to 800.0	-328.0 to 1472.0	(C Do	
		4	1	E(CR).H	-200 to 800	-328.0 to 1472	se	
Thermocouple	E(CR)	5	0.1	E(CR).L	-200.0 to 800.0	-328.0 to 1472.0	(D	
	T(CC)	6	1	T(CC).H	-200 to 400	-328 to 752	Pr se	
	T(CC)	7 0.1 T(CC).L		T(CC).L	-200.0 to 400.0	-328.0 to 752.0		
	B(PR)	8 1 E		B(PR)	0 to 1800	32 to 3272	(E Pi	
	R(PR)	9	1	R(PR)	0 to 1750	32 to 3182	se	
	S(PR)	10	1	S(PR)	0 to 1750	32 to 3182	(F	
	N(NN)	11	1	N(NN) -200 to 1300		-328 to 2372	R	
	C(TT) <sup>×1</sup>	12	1	C(TT)	0 to 2300	32 to 4172		
	G(TT) <sup>%2</sup>	13	13 1 G(TT) 0 to 2		0 to 2300	32 to 4172	(G) Con	
		14	1	L(IC).H	-200 to 900	-328 to 1652	S	
	L(IC)	15 0.1 L(IC).L -200.0 to 9		-200.0 to 900.0	-328.0 to 1652.0	(H		
		16	1	U(CC).H	-200 to 400	-328 to 752	(H Te co	
	U(CC)	17	0.1	U(CC).L	-200.0 to 400.0	-328.0 to 752.0		
	Platinel II	18	1	PLII	0 to 1400	32 to 2552	(I) S: Po	
	JPt 100Ω	19	1	JPt100.H	-200 to 600	-328 to 1112	CC	
RTD	JF1 10012	20	0.1	JPt100.L	-200.0 to 600.0	-328.0 to 1112.0		
	DPt 100Ω	21	1	DPt100.H	-200 to 600	-328 to 1112	(J Co	
		22	0.1	DPt100.L	-200.0 to 600.0	-328.0 to 1112.0		

※1. C(TT) : Same as existing W5(TT). :X2. G(TT) : Same as existing W(TT). ※Default : K(CA).H

#### Error indication

	Input sensor open error	Over temperature range
PWR LED	Red ON	
CH1 LED	RED Flashing (for 0.5 sec.)	
CH2 LED	RED Flashing (for 0.5 sec.)	
CH3 LED <sup>×1</sup>	RED Flashing (for 0.5 sec.)	
CH4 LED <sup>×1</sup>	RED Flashing (for 0.5 sec.)	
Communication output (decimal)	'31000' output	'30000 (upper limit)' output, '-30000 (lower limit)' output
Dedicated program	'OPEN' indication	'HHHH (upper limit)' indication , 'LLLL (lower limit)' indication

%1. Only for TM4 Series(4CH).

# Communication setting

# ◎ A function for external parameter setting & monitoring with PC or PLC.

•	Interface

Compliance with EIA RS 485
31 units(communication address setting: 01 to 31)
Two wire, Half Duplex
Asynchronous
Max. 800m
2400, 4800, 9600(default),19200, 38400
5 to 99ms
1bit(fixed)
1bit, 2bit(default)
None(default), Odd, Even
8bit(fixed)
Modbus RTU

XOverlapped address setting is not allowed on the same communication line.

Twisted Pair wires(for RS485 communication) must be used for communication cable.

Communication speed indication

①Current communication speed will be flashing in case of initial power ON for 5 sec. (1 sec. cycle).

PWR 💭
2400
4800
-📛 9600
19200
38400

XOne module communication is allowed for Port A. Communication speed is fixed to 9600bps. Multiple communication is allowed for Port B. It is required to reset controller's Power(Power OFF -

Power ON) after changing communication speed. Simultaneous monitoring can not be done for Port A and B since Port A is for parameter setting only.

% If connects communication through Port A, Port B will be disconnected communication automatically.

(K) Timer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching

power supply

(Q) Stepping motor& Driver&Controller

(R) Graphic/

(T) Software

(U) Other

Logic panel (S) Field network device

•Communication address setting ①Set the communication address using SW1 and SW2.

Setting range is 01 to 31. (XIn case setting 00, communication is not available.)

SW1 SW2								A 5	×Defa	ault : S	SW1 :	1, SW	/2 : +0	)		
	0	1	2	3	4	5	6	7	8	9	А	В	С	D	E	F
+0+16		01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
+0 +16	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31

**CE** 

# Sold separately

#### •Communicatoin converter

[SCM-38I(RS232C to RS485 converter)] [SCM-US48I(USB to RS485 converter)]

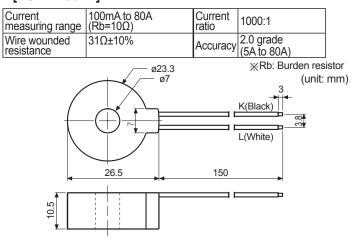
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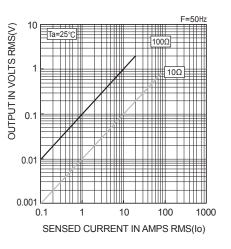




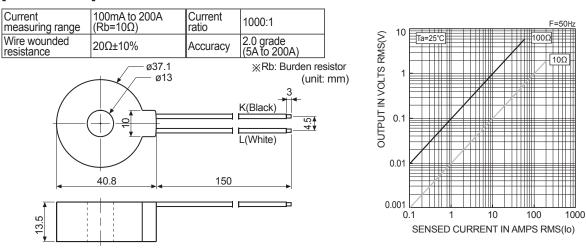


#### Current transformer(CT) [CSTC-E80LN]





#### [CSTC-E200LN]



\* Do not supply primary current in case that CT output is open. High voltage will be generated in CT output.

# Proper usage

#### Simple failure diagnosis

- •When indicating LED is flashing every 0.5 sec. or when error message is indicated on external units
- ①It represents input sensor open error. Cut off the power of controller and check input sensor connection.

If sensor is properly connected, disconnect sensor line from the controller and short the input terminal (+) / (-). Then, make sure that current indoor temperature is indicated. If current indoor temperature is properly indicated, it represents no errors detected. If external unit displays 'HHHH' or 'LLLL', please contact our A/S center.(Current indoor temperature checking is available only if selecting thermocouple type.)

②Make sure proper input sensors are selected.

When no output is operated

①Check output indicating LED at the front. In case output indicating LED does not work properly, please check each parameter setting again. In case output indicating LED works properly, disconnect the output terminal and check controller's output type (Relay contact, SSR, Current) again.

•When external units receive no response or error data ①Check communication converter first. [RS232C to

- RS485 converter(SCM-38I, sold separately), USB to RS485 converterserial(SCM-US48I, sold separately) USB to Serial converter(SCM-US, sold separately)] ②Do not install the unit with overlapping communication
- converter lines and AC power supply lines.
- ③Use separate power supply (24VDC) for communication converter if possible.
- (4) Strong external noise could be a possible cause for this symptom. Please contact our A/S center. In addition, analyze the main cause that triggers strong noise and take measures to prevent it. Even though this unit complies with proper noise resistance standards, consistent noise induction could affect internal circuit break.

•When communication does not work properly

①Check converter's power supply and connection.

- ②Check communication setting.
- ③Check main body's connections to external units.

#### © Caution for using

- 1. Use DC power only.
- 2. Keep the ambient temperature -10°C to 50°C
- 3. For more accurate controlling, start temperature controlling approx. 20 minutes later after connecting input sensors and supplying power.
- 4. In case indicating accuracy does not meet the specification, check Input Bias parameter first.
- 5. Power switch or a circuit breaker must be installed for proper application.
- 6. Make sure that the power switch or a circuit breaker installed near operators.
- 7. This unit is solely allowed for temperature controlling application. Do not apply this unit as a voltage meter or current meter.
- 8. When line extension is required, please use specified compensation line. If not, there occurs temperature difference at the joint part between thermocouples and extension lines.
- 9. In case of using RTD, line connection must be done with 3 wires. When line extension is required, use the same wire with material, thickness and length. Different line resistance may cause temperature difference.
- 10. Make sure controller's line connection must be separated from high voltage line or power supply line in order to prevent induced noise.
- 11. If it is required that power supply line should be connected near input signal line, use line filter on controller's power supply line and input signal line must be shielded.
- 12. Avoid installing controllers adjacent to high frequency noise generating units including high frequency soldering machine, high frequency sewing machine, and high capacity SCR controllers and motors.
- 13. Avoid using the unit near radio, TV or wireless machines that may cause high frequency interference.
- 14. When changing input sensors, power off the controller first. Connect input sensors as specified and supply the power again. Then, change & download related parameters using PC loader program.
- 15. Use (-) driver screws (2mm) or use plastic driver screws. If not, it might cause product damage.
- 16. Twist Pair wires must be used for communication cable. Connect Ferrite Bead at each end of line in order to reduce the effect of external noise.
- 17. Avoid installing the unit with overlapping communication line and AC power line together.
- 18. Draw a draft while using the controllers. In case of installing at a closed area, please take measures for ventilation.
- 19. Installation environment
  - (1) It shall be used indoor. ②Altitude Max. 2000m. ③Pollution Degree 2 (4) Installation Category II.
- %Please keep the above precautions to avoid malfunction and damages.

(F) Rotary encoder (G) nector/ Socket (H) Temp. controlle SR/ Power controller (J) Counter (K) Timer (L) Panel reter (M) Tacho/ Speed/ Pulse meter (N) Display unit

(A) Photo

electric sensor

(B) Fiber

optic

(C) Door/Area sensor

(D) Proximity sensor

Pressure

sensor

Sensor controller

(P) Switching power supply

(Q) Stepping motor& Driver&Controller

(R) Graphic/ Logic panel

(S) Field

network device

(T) Software

(U) Other