Ultra-slim and amplifier built-in type

Features

- Realization of ultra-slim size by adopting one-chip photo IC
- Size: Through-beam(W13×H19×L3.7mm),
 - Diffuse reflective, BGS reflective(W13×H24×L3.7mm)
- Adopts BGS method superior than convergent reflective to minimize error by background color, or material of sensing object for stable sensing
- Visible light source to check the position of sensing spot and superior to small sensing target with narrow sensing width
- · Built-in reverse polarity, output short, overcurrent protection circuit
- Protection structure IP67(IEC standard)

Please read "Caution for your safety" in operation manual before using.

Specifications

1 g	IPN open collector output	BTF1M-TDTL	BTF1M-TDTD	BTF30-DDTL	BTF30-DDTD	BTF15-BDTL	BTF15-BDTD	
≗	NP open collector output	BTF1M-TDTL-P	BTF1M-TDTD-P	BTF30-DDTL-P	BTF30-DDTD-P	BTF15-BDTL-P	BTF15-BDTD-P	
Sensing type		Through-beam		Diffuse reflective		BGS reflective		
Sensing distance		1m		5 to 30mm (Non-glossy white paper 50×50mm)		1 to 15mm (Non-glossy white paper 50×50mm)		
Sensing target		Opaque materials of max. ø2mm		Opaque materials, Translucent mater		ials		
Min.sensing target		Opaque materials of ø2mm		ø0.2mm (Sensing distance 10mm)		Ø0.2mm non-illuminated objects (Sensing distance 10mm)		
Hysteresis		—		Max. 20% at rated sensing distance		Max. 5% at rated sensing distance		
Reflectivity characteristics (black/white error)		_				Max. 15% of maximum sensing distance		
Response time		Max. 1ms						
Power supply		12-24VDC ±10%(Ripple P-P: Max. 10%)						
Current consumption		Max. 20mA(This is for each emitter and receiver of through-beam type)						
Light source		Red LED(650nm)						
Operation mode		Light ON	Dark ON	Light ON	Dark ON	Light ON	Dark ON	
Control output		NPN or PNP open collector output •Load voltage: Max. 26.4VDC •Load current: Max. 50mA •Residual voltage - NPN:Max. 1V, PNP:Max. 2V						
Protection circuit		Reverse polarity protection, output short-circuit protection						
Indicator		Operation indicator: Red, Stability indicator: Green						
Insulation resistance		Min. 20MΩ(at 500VDC megger)						
Noise resistance		±240V the square wave noise(pulse width:1µs) by the noise simulator						
Dielectric strength		1,000VAC 50/60Hz for 1 minute						
Vibration		1.5mm or 300m/s ² amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours						
Shock		500m/s ² (50G) in each of X, Y, Z directions for 3 times						
Fourier	Ambient illumination	Sunlight: Max. 10,0001x Incandescent lamp: Max. 3,0001x (Receiver illumination)						
ment	Ambient temperature	-25 to 55°C, storage: -40 to 70°C						
	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH						
Protection		IP67(IEC standards)						
Material		Case: PBT, Sensing part : PMMA						
Cable		ø2.5mm, 3-wire, Length: 2m (Emitter of through-beam type: ø2.5mm, 2-wire, Length: 2m) (AWG28, Core diameter: 0.08mm, Number of cores: 19, Insulator out diameter: ø0.9mm)						
Acce	ssory	Fixing bracket(SUS304), Bolt(SWCH10A)						
Approval		CE						
Unit weight		Approx. 40g		Approx. 25g				

Dark ON model

Line-up

Through-beam

X The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

Feature data O Through-beam **O** Diffuse reflective BTF1M-TDTL / BTF1M-TDTL-P BTF30-DDTL / BTF30-DDTL-P Sensing area characteristic Sensing area characteristic Measuring method Data Measuring method Data 1.8 50 1.6 45 Sensing distance L(mm) Sensing distance L(mm) 1.4 40 1.2 35 Emitter Standard 1.0 30 sensing target 0.8 25 ℓ1 0.6 20 0.4 15 È Ē 0.2 10 Receiver Æ 0₃ 0 40 20 0 -20 -40 -60 0 2 1 -1 -2 -3 *ℓ*1 *ℓ*1 *l*1 *l*1 Sensing area (mm) Sensing area (mm) O BGS reflective BTF15-BDTL / BTF15-BDTL-P Sensing area characteristic Sensing distance by material Measuring method Data 18 20 16 Sensing distance L(mm) 14 Sensing distance L(mm) 15 12 Standard 10 sensing target 10 9 5 6 T 4 0 2 PCB (green) Acryl (transparent) White Black SUS304 0 paper paper -1 ℓ1 Ż 0 ÷2 3 1 ℓ1 -3 Sensing target(material) Sensing area (mm) Connections Control output diagram Through-beam NPN open collector output

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Diffuse reflective/BGS reflective



※ 1: Load connection for NPN output



PNP open collector output



(B) Fibe

optic

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure

sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching

power supply

(Q) Stepping

(R) Graphic/

Logic panel

motor& Driver&Controller

Operation mode

Operation mode	Light ON	Dark ON		
Beasiver energian	Received light	Received light		
Receiver operation	Interrupted light	Interrupted light		
Operation indicator	ON	ON CON CONTRACTOR ON CONTRACTO		
(red LED)	OFF	OFF		
Transistor output	ON	ON CON CONTRACTOR ON CONTRACTO		
Transistor output	OFF	OFF		

Dimensions

• Through-beam





• Diffuse reflective/BGS reflective







Operation timing diagram



% The waveforms of "Operation indicator" and "Transistor output" are for Light ON operation. They are opposite operation for Dark ON operation.

Mounting and sensitivity adjustment

O For mounting

Please use bolts M2 for mounting this sensor and the tightening torque is under $0.3 \text{ N} \cdot \text{m}$.

※ Do not impact on the unit with hard objects and do not bend the cable part too much. It may cause damage to waterproof function.

Through-beam



• Diffuse reflective/BGS reflective



Optical axis adjustment

• Through-beam

Set the emitter and the receiver facing each other and adjust these up down, right-left after to check the point operating the stability indicator. Fix the emitter and the receiver at the center of the point.



% Notice for BGS reflective type

- Make sure that the sensing side of this sensor is parallel with the surface of each sensing object.
- 2) If the sensing object has 5 to 10° glossary surface or highreflection, the sensor tilts to 5 to 10°as shown in the figure. Make sure whether the sensor is influenced by any background objects.
- 3)Make sure to install the sensor in the proper direction with considering moving direction of sensing objects. Refer to the following.

Glossy materials



• Diffuse reflective/BGS reflective

After place a sensing target, fix it in the middle of position where the stability indicator operates adjusting the sensor to $up \cdot down$, right-left. Make sure that the sensing side of the sensor is parallel with the surface of each sensing target.



optic (C) Door/Area sensor (D) Proximity sensor (E) Pressure sensor (F) Rotary encode (G) Connector/ Socket (H) Temp. controller (I) SSR/ Power controller (J) Counter Sensing target (K) Timer (L) Panel meter (M) Tacho/ Speed/ Pulse meter (N) Display unit (O) Sensor controller (P) Switching power supply (Q) Stepping motor& Driver&Controlle (R) Graphic/ Logic panel (S) Field network device (T) Software

Autonics

(U) Other