Dual PID auto tuning control

Features

- Dual PID auto tuning function : High-speed response of PID control to reach to the desired value fast, low-speed of response of PID control to minimize the overshoot even though response is a little bit slow.
- High display accuracy : ±0.3%(by F.S. value of each input)
- 2-Steps auto tuning control function
- Multi-input function(13 kinds of multiinput selection function) : Temperature sensor, voltage and current selection function.
- Various sub output function : Includes in LBA, SBA, 7kinds of alarm output and 4 kinds of alarm option function, PV transmission output(DC4-20mA), RS485 communication output
- Display the decimal point for analog input

Please read "Caution for your safety" in operation manual before using.



Ordering information

ΓZ	4	м —	1	4	R			
					Control	outout	R	Relay contact output
					Control	ιοιιριι	S	SSR drive output
							с	Current output(DC4-20mA)
				Pow	ver supply $^{\times 1}$		2	24VAC/24-48VDC
							4	100-240VAC 50/60Hz
						TZ4SP/TZN4S	1	Event 1 output
							1	Event 1 output
						12451	2	Event 1 + Event 2 output
			Sub ou	utput		_	R	Event 1 + PV transmission output(DC4-20mA)
							1	Event 1 output
							2	Event 1 output
						Etc.	R	Event 1 + PV transmission output(DC4-20mA)
							А	Event 1 + Event 2 + PV transmission output(DC4-20mA)
							т	Event 1 + RS485 communication output
							в	Event 1 + Event 2+RS485 communication output
						TZN4	S	DIN W48×H48mm(Terminal type)
						TZ4	SP	DIN W48×H48mm(Plug type)
		Size				_	ST	DIN W48×H48mm(Terminal type)
							м	DIN W72×H72mm
						TZ4/TZN4	w	DIN W96×H48mm
							н	DIN W48×H96mm
							L	DIN W96×H96mm
	Digit						4	9999(4 digit)
Item							TZ	Temperature dontroller(PID)
							TZN	Temperature dontroller (PID New type)

%1. Only for TZ4SP, TZ4ST, TZ4L, TZN4M Series.

Specifications

Sp	ecificatio	ns									(A) Photo
Series		TZ4SP	TZN4S	TZ4ST	TZ4M	TZN4M	TZ4W TZN4W	TZ4H TZN4H	TZ4L	TZN4L	electric sensor
Power	AC Power	100-240VAC 5	50/60Hz	•		1					(B) Fiber
supply	AC/DC Power	24VAC 50/60H		BVDC							sensor
Allowable	e voltagerange	90 to 110% of	power su	ıpply							(C)
		Max. 5VA			Max. 6	Max. 6VA					Door/Area sensor
Power co	onsumption	AC: Approx. 8VA, DC: Max. 7W		AC: Approx. 8VA, DC: Max. 7W	—	AC: Approx. 8VA, DC: Max. 7W			AC: Approx. 8VA, DC: Max. 7W		(D) Proximity
Display ı	method	7Segment LED	Display	[Process value(PV) : Red, Setting value(SV) : Green]						sensor	
Character size		TZ4SP- W4.8×H7.8mm TZN4S - PV:W7.8×H11m SV:W5.8×H8mr	ım n	W4.8×H7.8mm	TZ4M - PV:W9. SV:W8> TZN4M PV:W8>	8×H14.2mm <h10mm - <h13mm< td=""><td colspan="2">m W8×H10mm TZV4H- PV:W7.8×H11mm SV/W5 8×H3mm</td><td colspan="2">PV:W9.8×H14.2mm SV:W8×H10mm</td><td>(E) Pressure sensor (F) Rotary</td></h13mm<></h10mm 	m W8×H10mm TZV4H - PV:W7.8×H11mm SV/W5 8×H3mm		PV:W9.8×H14.2mm SV:W8×H10mm		(E) Pressure sensor (F) Rotary
	Thermocouple	K(CA), J(IC), R	(CA), J(IC), R(PR), E(CR), T(CC), S(PR), N(NN), W(TT) <tolerance 100ω="" a="" is="" line="" max,="" of="" per="" resistance="" wire=""></tolerance>								encoder
Input	RTD	DPt100Ω, JPt1	00Ω. 3wi	re <tolerance o<="" td=""><td>f line res</td><td>istance is max.</td><td>5Ω per a wire</td><td>></td><td>•</td><td></td><td>(G) Connector</td></tolerance>	f line res	istance is max.	5Ω per a wire	>	•		(G) Connector
	Analog	1-5VDC. 0-10\	/DC. DC4	1-20mA							Socket
Relav 250VAC 3A 1c								(H)			
Control	SSR	12VDC + 3V 30									
output	Current	DC4-20mA(Resistive load Max. 600Ω)									
	Transmission	PV transmission · DC4-20mA Load max 6000									SSR/ Power
		250)/AC 1A 1a	250VAC 1A 1a								
Sub		250VAC TA TA		250 / 0 0 1 0 1 0							(J)
output	EVEN12			250VAC 1A 1a	00405		- <u>O) (#:)</u>				Counter
Constral a					R5485	(PV transmission	n, Sv setting)				(K)
	netnod	UN/OFF contro		D, PIDF, PIDS							Timer
Setting type Erept puck buttope											
Setting t	ype								Panel meter		
Hysteres	SIS	Adjustable 1 to	0 100°C(0.	.1 to 100.0°C) at		F control					
Alarm ol		Adjustable ON	/OFF 1 to	100 (0.1 to 100	0.0)°C of	alarm output					(M) Tacho/
Proportio		0.0 to 100.0%									meter
Intergral	time(I)	0 to 3600 sec.									(N)
Derivativ	ve time(D)	0 to 3600 sec.									Display unit
Control t	lime(I)	1 to 120 sec.									(0)
RAMP s	etting	0.5 sec.									(U) Sensor
LBA sett	ing	1 to 999 sec.									controller
RAMP s	etting	Ramp Up, Ran	np Down	at 1 to 99min.							(P) Switching
Dielectri	c strength	2000VAC 50/6	0Hz for 1	min.							supply
Vibratior	۱ ایر ا	0.75mm amplit	tude at fre	equency of 10 to	55Hz(fc	or 1 min.) in each	n of X, Y, Z dir	ections for 2 hou	Irs		(Q) Stopping
Relay	Main output	Mechanical : N	1in. 10,00	0,000 operation	s, Electri	ical : Min. 100,00	00 operations	(250VAC 3A resi	stive load)		motor& Driver&Cor
life cycle	Sub output	Mechanical : N	1in. 20,00	0,000 operation	s, Electri	ical : Min. 300,00	00 operations	(250VAC 1A resi	stive load)		(R)
Insulatio	n resistance	Min. 100MΩ(at	t 500VDC	; megger)							Graphic/ Logic
Noise		Square shaped	d noise by	/ noise simulato	r(pulse v	vidth 1µs) ±2kV					panel
Memory	protection Ambient	Approx. 10yea	rs(When	using non-volati	le semic	onductor memo	ry)				(S) Field network
Environ -ment	Ambient	35 to 85%RH.	storage: 3	35 to 85%RH							(T)
Approva	 		-								Software
Unit weig	ght	TZ4SP: Approx. 136g TZN4S: Approx. 150g		Approx. 136g	Approx.	. 270g	TZ4W: Approx. 270g TZN4W: Approx. 259g	Approx. 259g	Approx. 360g		(U) Other

%1. Low voltage is only for TZ4SP, TZ4ST, TZN4M, TZ4L series. *Environment resistance is rated at no freezing or condensation.

Connections

RTD(Resistance Temperature Detector): DPt100 Ω (3-wire type), JPt100 Ω (3-wire type) RT.C(Thermocouple): K, J, R, E, T, S, W, N In case of Analog input, please use T.C(Thermocouple) terminal and be careful about polarity.



Autonics

Dual PID Auto Tuning Control



Dimensions



% Since TZ4SP uses same indentification plate with TZ4ST, the lamp does not work even though it has a EV2 output signal lamp.











© TZ4W







Dual PID Auto Tuning Control



Flow chart for setting group 1

RUN	If press MD ke	ey for 3sec. T	his mode changes to first flow chart.
<u>50-2</u>	SV-2 (Setting value 2)	0	Set alarm temperature in SV2 within the rated using range of each sensor.
ÂL I	AL1 setting value	10	Set alarm temperature in EV-1 within the rated using range of each sensor.
	AL2 setting value	10	Set alarm temperature in EV-2 within the rated using range of each sensor.
LLA	Loop break alarm	999	Set monitoring time of loop break alarm within 0 to 999sec.
RHYS	Alarm hysteresis	2	Set Interval between ON and OFF for alarm output from 1 to 100°C (Decimal type : 0.1 to 100.0°C). It is only displayed for temperature alarm output.
P	Proportional band	3.0	Set Proportional band from 0.0 to 100.0%. If setting value P as 0.0, it will be ON/OFF control.
	Integral time	0	Set Integral time from 0 to 3600 sec.If setting value I as 0 sec. This function will be OFF. It is not displayed when P is 0.0. (ON/OFF control)
, , , , , , , , , , , , , , , , , , ,	Derivative time		Set Derivative time from 0 to 3600 sec.If setting value D as 0 sec. This function will be OFF. It is not displayed when P is 0.0. (ON/OFF control)
	Control time	20	Set control period cycle from 1 to 120 sec. In case of SSR output, this value should be small.(Ex : 2sec.) It is not displayed when P is 0.0. (ON/OFF control)
HYS	Hysteresis	2	When the ON/OFF control function used. Set Hysteresis from 1 to 100°C(Decimal type : 0.1 to 100.0°C)
1 n-b	Input correction	0	Correct the error in input sensor from -49 to 50°C (Decimal type : -50.0 to 50.0°C)
rESE	Manual reset	0.0	Set Manual reset value from 0.0 to 100.0% This is for P control only, not for PID.
r ÂPU	RAMP rising RAMP-up time	10	Set Ramp rising-time from 1 to 99 min. It displayed only when selecting Ramp function in setting 2 group.
r ÅPd	RAMP falling RAMP-down time	10	Set Ramp falling-time from 1 to 99 min. It is displayed when selecting Ramp function at setting group 2.
	Lock		Cancel the Lock function for OFF.
		on	This function is for locking the setting value.(Available to operate \fbox{AT} Key)
		on I	Select ON1, changing setting value in the setting group 1and AT key in the front panel cannot be changed.

 \times It will start to flash by pressing \blacksquare (**《**) key and the flash will be moved by \blacksquare (**《**), \blacktriangleright (**》**) keys then set the value *It returns to RUN status in case of pressing MD key for 3sec. after setting all mode to change.

% If no key touched for 60sec., it will return to RUN mode automatically.

XIf not to set related mode in setting group 2, AL I, AL 2, L bA, I, d, E, HY5, r E 5E, r APU, r APdmode will disappear and then jump to next mode.

Factory defaults(Setting group 1)

Mode	Setting value	Mode	Setting value	Mode	Setting value	Mode	Setting value
58-2	0	RXYS	2	Ł	20	r RPU	10
AL I	10	ρ	3 <u>,0</u>	H Y S	2	r RPd	10
ALS	10	1	0	10-6	0	Lo[oFF
L Ь Я	600	d	0	rESt	0.0		

Flow chart for setting group 2

RUN	If press	sing 🔟 + 🖄	key for 3sec.	at once in I	RUN state, it	will go to settin	ng group 2.				
Input type	Event 1 mode	(Note) Event 2mode	Alarm type	Auto- tuning type	PID type	Control operating Ter type	nperature unit	Scaling high limit	Scaling low limit	(★) Decimal point	
!	EU- 1	→ <i>EU-2</i>	→ <i>AL - F</i>	AF'F	• <i>Pi d</i> Ł	• o-FŁ	Uni Ł⇒	H-S[[™]	• <u>L - 5</u> [σοε]
	$ \begin{array}{c} LbA \\ \uparrow \boxtimes \downarrow \boxtimes \\ SbA \\ \uparrow \boxtimes \downarrow \boxtimes \\ AL - 0 \\ \hline AL - 1 \\ AL - 1 \\ AL - 1 \end{array} $	<i>L b R</i> ↑ ⊠ ↓ <i>B</i> 5 <i>b R</i> ↑ ⊠ ↓ <i>B</i> <i>A L</i> − <i>D</i> ↑ ⊠ ↓ <i>B</i> <i>A L</i> − <i>J</i>	AL-A ↑ ₪↓ @ AL-b ↑ ₪↓ @ AL-C ↑ ₪↓ @ AL-d	<u>Fnus</u> Fnus	Pi d.S ↑⊎↓≋ Pi d,F	HERE ↑⊎↓≈ Cool	o£ 0[1300	- 100	↑ ♥ ↓ ∅ ↑ ∅ ↓ ∅ ↑ ∅ ↓ ∅ ↑ ∅ ↓ ∅ ↑ ∅ ↓ ∅ 0.000	
$ \begin{array}{c} \uparrow \boxtimes \downarrow \boxtimes \\ \hline r & Pr \\ \hline E & r & H \\ \hline E & r & H \\ \hline E & r & H \\ \hline E & r & L \\ \hline I & I & I \\ \hline E & r & L \\ \hline I & I & I \\ \hline I$	$\begin{bmatrix} \mathbf{R} \mathbf{L} - \mathbf{Z} \\ \mathbf{R} \mathbf{R} \mathbf{L} - \mathbf{Z} \\ \mathbf{R} \mathbf{R} \mathbf{R} - \mathbf{R} \\ \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \\ \mathbf{R} \mathbf{R} \mathbf{R} \\ \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \\ \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} - \mathbf{R} \\ \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \\ \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R} \mathbf{R}$	$ \begin{array}{c} \uparrow \blacksquare \downarrow \blacksquare \\ RL - 2 \\ \uparrow \blacksquare \downarrow \blacksquare \\ RL - 3 \\ \uparrow \blacksquare \downarrow \blacksquare \\ RL - 4 \\ \uparrow \blacksquare \downarrow \blacksquare \\ RL - 5 \\ \uparrow \blacksquare \downarrow \blacksquare \\ RL - 5 \\ RL - 6 \\ \end{array} $	 	Input type		Address ■ Address ■ Adr 5 ← []	Bit per second 6PS ↔ 9600 ↑ ₩ ↓ ₪ 4800 ↑ ₩ ↓ ₪ 2400	Ramp function FR ∩P OFF ↑ ♥ ↓ ₪ O ∩	Transmission output low limit F5-L - 100	E Transmission output high limit F5-H I300	
		lo-t	Input type : Se	lect from 19	tvpe		1-55	Set scalin	a low limit (In	clude analog ou	utput)
JPŁ ₩ ↑ ⊠ ↓ ⊠		EU-1	Event 1 : Selec	ct from 9 type	e		dot	Select de	cimal point po	osition for Analog	g input
		EU - 2	Event 2 : Selec	ct from 9 type	e		F5 - H	Set the hi	gh-limit when	retransmission	output
<u>dPLH</u>		AL-F	Alarm type : Se	elect from 4 t	уре		FS-L	Set the lo	w-limit when (4mA)	retransmission of	output
<u>dP£i</u>		AF.F	Auto-tuning : S	electable tur	n1 or tun2.		r R ñ P	Able to se	et ON and OF	F of Ramp func	tion.
1 8 1 -	7	PIdE	PID : Selectab	le PIDF or P	IDS		695	Set comm	nunication spe	eed	
		o-Ft	Selectable hea	at-function or	cool-function		RdrS	Set comm	nunication add	dress(01 to 99)	
	×1	Uni E	Temperature u	nit: °C or °F			Lo[The data the lock k	cannot be ch ey is ON	anged when	
H J -	_	H-5[Set scaling hig	h limit (Inclu	de analog out	put)					

 \times It will start to flash by pressing \bullet (\bigstar) key and the flash will be moved by \bullet (\bigstar), \triangleright (\gg) keys then set the value by \bullet (\bigstar), \bigtriangledown (\checkmark), keys. After that if pressing MD key the DATA will be changed then display next mode.

* It returns to RUN status in case of pressing MD key for 3 sec. after setting all mode to change.

If no key is touched for 60sec. in each mode, it will return to RUN mode automatically.

※RL 1, RL2, LbR, I, d, E, Hy5, FE5E, FRPU, FRPd modes are not displayed depending on the result of setting group 1. 2 and then jump to next mode.

×1. This is displayed only when input Sensor/Voltage/Current switch is voltage or current.

2. This is displayed only for model with High/Low-limit of transmission output.

Factory defaults (Setting group 2)

Mode	Setting value	Mode	Setting value	Mode	Setting value	Mode	Setting value
1 n - E	F C B'H	AT - F	A L - A	PI dE	PidS	H-5[1300
EU-1	AL - 1	RE.E	tun l	o - F E	HEAF	L-5[- 100
EU-2	AT - 5	r AñP	oFF	Unit	٥٢	Loĺ	oFF

 (C)
 Door/Area

 Door/Area
 sensor

 (D)
 Proximity

 sensor
 (F)

 Pressure
 sensor

 (F)
 Pressure

 Sensor
 (G)

 (Connector/
 Socket

 (G)
 Controller

 (I)
 SSR/

 Controller
 (J)

 (J)
 Counter

 (K)
 Timer

 (M)
 Speed/ Pulse

 meter
 Nisplay

 (N)
 Sensor

 (O)
 Sensor

(P) Switching power supply (Q) Stepping

motor& Driver&Controller

(R) Graphic/

Logic panel

(S) Field

network device

(T) Software

(U) Other

(A) Photo electric sensor

(B) Fiber optic sensor

Input type and range

Input type		Display	Input range(°C)	Input range(°F)
	K(CA) H	YCRH	-100 to 1300°C	-148 to 2372°F
	K(CA) L	FCUL	-100.0 to 999.9°C	This mode cannot be used as °F
	J(IC) H	J IC.H	0 to 800°C	32 to 1472°F
	J(IC) L	J IC.L	0.0 to 800.0°C	This mode cannot be used as °F
	R(PR)	r Pr	0 to 1700°C	32 to 3092°F
Thermonounle	E(CR) H	E[r.H	0 to 800°C	32 to 1472°F
Thermocoupie	E(CR) L	E[r.L	0.0~800.0℃	This mode cannot be used as °F
	T(CC) H	ECC.H	-200 to 400°C	-328 to 752°F
	T(CC) L	ECC.L	-199.9 to 400.0°C	This mode cannot be used as °F
	S(PR)	5 Pr	0 to 1700°C	32 to 3092°F
	N(NN)	N nn	0 to 1300°C	32 to 2372°F
	W(TT)	U EE	0 to 2300°C	32 to 4172°F
	JPt 100Ω H	JPE.H	0 to 500°C	32 to 932°F
DTD	JPt 100Ω L	JPEL	-199.9 to 199.9°C	-199.9 to 391.8°F
RID	DPt 100Ω H	dPt.H	0 to 500°C	32 to 932°F
	DPt 100Ω L	dPLL	-199.9 to 199.9°C	-199.9 to 391.8°F
	0-10VDC	81	-1999 to 9999°C	-1999 to 9999°F
Analog input	1-5VDC	82	-1999 to 9999°C	-1999 to 9999°F
	DC4-20mmA	R 3	-1999 to 9999°C	-1999 to 9999°F

Selection switch for Input sensor/Voltage/Current

A) In case of sensor input <k(ca), 100ω="" 100ω,="" dpt="" e(cr),="" j(ic),="" jpt="" n(nn),="" r(pr),="" s(pr),="" t(cc),="" w(tt),=""></k(ca),>										
S/W	1		S/W2							
S/W1:	1 1	1 mA V	S/W2:V							
B) In case of voltage input <1-5VDC, 0-10VDC>										
0.00			0.000							
5/00	╵──┼┿┿		S/WZ							
S/W1:	2 2	2 mA V	S/W2:V							
C) In case of current i	nput <dc4-20n< td=""><td>nA></td><td></td><td></td></dc4-20n<>	nA>								
	-									
S/W			S/W2							
S/W1:	2 2	2 mA V	S/W2:mA							

*Factory specification of Input sensor/Voltage/Current conversion switch : Temperature sensor input.

% Please select B) or C) according to input specification when it is voltage or current.

Alarm output function

This unit has output for control and sub(alarm) output. Sub output is optional. (This alarm output is relay contact(1a) and operates regardless of output for control.) Alarm output operates when the temperature of target is getting higher or lower than setting value.

- 1 alarm mode can be selected among 7 kinds of alarm mode at EV-1(EV-2) in the setting group 2.
- Since EV-1 and EV-2 operate separately, both EV-1 and EV-2 can be used as a high or low 2nd alarm operation.
- When selecting L b R or 5 b R function in EV-1(EV-2) of EV-1, alarm cannot be operated.
- Please note below "Operation chart for alarm output" & "Option of alarm output" for detailed operation and optional operation.

Alarm mode

Mode	Name	Alarm operation		Description	(F) Rotary
AL - D	—	—		No alarm output	encoder
AL-1	Deviation high-imit alarm	Alarm(Deviation)temperature:10°C OFF H ON SV100°C PV110°C	Alarm(Deviation)temperature:-10°C OFF H ON PV90°C SV100°C	If deviation between PV and SV as high- limit is higher than set value of deviation temperature, the alarm output will be ON.	(G) Connector/ Socket (H) Temp. controller
AF - 5	Deviation Iow-limit alarm	Alarm(Deviation)temperature:10°C	Alarm(Deviation)temperature:-10°C ON ↑ H ↓ OFF ▲ Δ SV100°C PV110°C	If deviation between PV and SV as low- limit is higher than set value of deviation temperature, the alarm output will be ON.	(I) SSR/ Power controller
	Deviation		mperature:10°C	If deviation between PV and SV as high/low-limit is higher than set value of	(J) Counter
AL-3	alarm		rrc PV110℃	deviation temperature, the alarm output will be ON.	Timer
	Deviation	Alarm(Deviation)te	mperature:10°C	If deviation between PV and SV as	(L) Panel meter
AL-4	high/low-limit reverse alarm	OFF H O	N	deviation temperature, the alarm output will be OFF.	(M) Tacho/ Speed/ Pulse meter
	Absolute value	Alarm (Absolute)temperature:90°C	Alarm (Absolute)temperature:110°C	If PV is equal to or higher than the	(N) Display unit
HL-5	high-limit alarm	OFF ↓ H ON A PV90°C SV100°C	OFF ↓ H ON ▲ △ SV100°C PV110°C	absolute value of alarm temperature, the output will be ON.	(O) Sensor controller
BL - 5	Absolute value low-limit	Alarm (Absolute)temperature:90°C	Alarm (Absolute)temperature:110°C	If PV is equal to or lower than the absolute value of alarm temperature, the	(P) Switching power supply
	alarm	PV90°C SV100°C	SV100°C PV110°C	output will be ON.	(Q) Stepping motor& Driver&Controlle

ж"b" is interval between ON and OFF the setting range is 1 to 100°C(0.1 to 100.0°C) and can be set at "Ану5" made in setting group 1.

■ Alarm option[*AL-E*]

Option	Name	Description
8ā-8	Standard alarm	If it is an alarm condition, alarm output is ON. If it is a clear alarm condition, alarm output is OFF.
Я л -Ь	Alarm latch	If it is an alarm condition, alarm output is ON and maintains ON status.(Alarm output HOLD)
Я <i></i> С	Standby sequence 1	First alarm condition is ignored and from second alarm condition, standard alarm operates. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, standard alarm operates.
Rō-d	Alarm latch and standby sequence 1	If it is an alarm condition, it operates both alarm latch and standby sequence. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, alarm latch operates.

Autonics

(A) Photo electric sensor

(B) Fiber

optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure

(R) Graphic/

Logic panel

(S) Field network device

(T) Software

(U) Other

sensor

Functions

O Auto tuning operation

PID auto tuning function automatically measures the thermal characteristics and response of the control system and then executes its value under high response & stability after calculating the time constant of PID required to control optimum temperature.

- Execute the auto tuning function at initial time after connecting the controller & the sensor.
- •Execution of auto tuning is started when pressing AT key for 3 sec. or more.
- •When the auto tuning is started, AT lamp will flash, and when the lamp is OFF, this operation will stop.
- •While the auto tuning function is executing, it is stopped by pressing AT key for 5sec. or more.

•When the power turns off or the stop signal is applied while auto tuning function is executing, time constant of PID is not changed and it remembers the value before power turns off.

• Time constant of PID selected by auto tuning function can be changed in setting group 1.

•It has two kinds of auto tuning mode. auto tuning operation is executed at setting value(SV) in TUN1 mode which is factory default. Auto tuning operation in TUN2 mode is executed in 70% of setting value (SV). Mode change is available in setting group 2.



•Execute the auto tuning function again periodically, because the thermal characteristics for the control object can be changed when the controller is used continuously for a long time.

Sub output(Event) function

Sub output can execute as main control output and sub function as well. There is one sub output in this unit.

- •This sub output is relay "1a" contact output.
- •1 mode can be selected among 7 kinds of alarm mode or LBA operated when the heater line is cut, SBA operated when the sensor line is cut.
- •The Sub output can be latched ON or automatically reset depending on the alarm option mode selected.
- •When the sensor line or the heater line is cut, SBA or LBA output turns on. This "Output on" status must be reset by turning the power off.

© Sensor Break Alarm(SBA) function

This function causes the sub output to turn on when the sensor line is cut or open. It is easier to check that whether the sensor line is cut or not through buzzer or etc by exterior sub output (relay contact).

• For using SBA function, set 5bR at Eu + or Eu2 in setting2 group and SBA output operates as EV1 OUT or EV2 OUT contact.

© Loop Break Alarm(LBA) function

LBA function is to diagnose an abnormal temperature of the control system. If the temperature of the control system is not changed within $\pm 2^{\circ}$ C during setting time of LBA, the LBA output will be ON.

Ex)When setting value(SV) is 300°C, process value(PV) is 50°C, this unit controls 100%.

In this time if there is no change of system temperature, it recognizes Heater is cut off then LBA output will be ON.

- •LBA output can be selected at EV1 of the setting group 2.
- •If LBR output is not selected at event output, it will not be displayed in setting group 1.
- •Setting range of *L B R* output is 1 to 999sec.
- If thermal response of the control system is slow, LBA value should be set to a high value.
- •LBA output operates when the manipulated value of the controller is 0% and 100%.
- •In case the LBA output is ON, please check the following;
- ①Short-circuit or cutting of the temp. sensor.
- ②Abnormal condition of the equipment
- (Magnet, sub-relay, etc.)

③Abnormal condition of the load(Heater, cooler)

- Wrong-wiring or cutting of the other cables.
- •Once SBA is ON due to broken sensor, it will not reset, although sensor is connected. In this case, turn off the power then turn on again.

© Error display

If error is occurred while the controller is operating, it will be displayed as follow.

- •"LLLL"is flashing when measured input temperature is lower than input range of the sensor.
- •"HHHH" is flashing when measured input temperature is higher than input range of the sensor.
- •" DPEn" is flashing when the input sensor is not connected or its wire is cut.

ON/OFF control

ON/OFF control is called two position control because the output turns on when PV falls lower than SV and the output turns off when PV is higher than SV.

This control method is not only for controlling temperature, but also it is basic control method for sequence control.

- •If you set value P as "<u>0</u>,0" in setting group 1, ON/OFF control will operate.
- •There is a programmable temperature difference between ON and OFF in ON/OFF control, if difference is too small, then hunting(chattering) can occur. Temperature difference can be set in HYS mode

of setting group 1. Setting range is 1 to 100(or 0.1 to 100.0).

- •H95 mode is displayed when P value is "<u>0.0</u>", but H95will not be displayed, and then jump if P value is not <u>0.0</u>.
- •This ON/OFF control should not be applied when equipment(Cooling compressor) to be controlled can be damaged by frequent ON and OFF.
- •Even if ON/OFF control is stable status, the hunting can be occurred by setting value in Hy5 or capacity of the heater or response characteristic of the equipment to be controlled or installing position of the sensor. Please consider above points to minimize the hunting when designing the system.

Manual reset function

Proportional control has deviation because rising time is not same as falling time, even if the unit operates normally. Manual reset function is used at proportional control mode only.

- •If set **rESE** function in setting group 1, the manual reset will run.
- •When PV and SV is equal, **rE5b** value is 50.0% and when control is stable, if the temperature is lower than SV, **rE5b** value should be higher and on the other hand, **rE5b** value should be smaller.
- •[*c***E5**b]setting method according to result of control.



© Dual PID control function

When controlling temperature, two types of control characteristic are available as below.

(A) Photo

electric sensor

(B) Fiber

(C)

Door/Area sensor

(D) Proximity sensor

(E) Pressure

sensor

(F) Rotary encoder

(G) Cor

émp.

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/

. meter

(N) Display unit

(O) Sensor controller

(P) Switching

power

supply

(Q) Stepping

(R) Graphic/

Logic panel

(S) Field

network device

(T) Software

(U) Other

motor& Driver&Controller

Speed/ Pulse

Connector/ Socket

optic

One is when you need to minimize the time which PV reaches to SV as like(Fig. 1). The other is when you need to minimize overshoot even though the reaching time(PV to SV) is slow(Fig. 2).

- •There are high-speed response type and lowspeed response type built in this unit. Therefore user can select each function according to their application.
- •You can select dual PID control function in setting group 2. It is selectable *Pl dF* or *Pl d5* in *Pl dE* mode. •*Pl dF*(High-speed response type)
- This mode is applied to machines or systems which require high-speed response.



•Pl d5(Low-speed response type)

It is PID Slow, used to minimize overshoot even though the response is slow.

For control temperature of oil, plating machine have a possibility of fire with overshoot, *Pl* d5 (Limi over) should be used.



※Factory default setting is *Pt d*5 Please select mode according to control system.

© RS485 communication function

It is used on the purpose that transmitting PV to an external equipment, setting SV at the external equipment.

- •It can be set at BP5, $Rd_{F}5$ in second setting group
- Communication speed(bps) setting: 2400, 4800, 9600bps
 Start bit(1bit, Fixed), Stop bit(1bit, Fixed), Parity bit(None)
- •(Rdr 5) setting : 1 to 99
- •If the external equipment is a PC(Personal Computer) using RS232C to RS485 converter(SCM-38I) sold separately.

◎ Decimal point [dot] setting function

Decimal point is displayed as "dot" in second setting group when the input is analog only. (0-10VDC, 1-5VDC, DC4-20mA)

◎ Cool/Heat function

Generally there are two ways to control temperature, one(Heat-function) is to heat when PV is getting down(Heater). The other(Cool-function) is to cool when PV is getting higher(Freezer).

These functions are operating oppositely when it is ON/OFF control or proportional control.

But in this case PID time constant will be different due to PID time constant will be decided according to control system when it is PID control.

- Cool-function and heat-function can be set at "Setting group 2".
- •Cool-function and heat-function must be set correctly according to the application, if set as opposite function, it may cause a fire.

(If set cool-function at heater, even if temperature is getting high, it will be maintained ON and it may cause a fire.)

- •Avoid changing heat-function to cool-function or cool-function to heat-function on the unit is operating.
- •It is impossible to operate both function at once in this unit. Therefore, only one function should be selected only.
- •Factory default setting is heat-function.

◎ SV-2 function

If using SV-2 function, it changes the temperature of control system to the second setting value by external relay contact signal. It can change the setting value as sequentially by relay contact without key operation.



- •It can set SV-2 at required time and particular area as like the above chart.
- •SV-2 is in setting group 1.
- •Application :

The control system, which has to maintain constant temperature such as oven. If you open the door, temperature will go down.

In this case, if you set the second setting value higher than setting value, temperature will rise fast. Therefore, after installing a micro-switch in order to detect the door Open/Close and connect it to SV-2(the second setting value should be higher than SV) then it controls temperature of oven efficiently.

© Ramp function

Ramp function is to delay the rising time or falling time of temperature. If you change setting value at stable state of control, it forces to rise or fall the temperature of control system during setting time at $_{\Gamma}R_{\Gamma}P$, $_{\Gamma}RPd$ in setting group 1.

If r A r P is not ON in setting group 2, r RPU, r RPJ will not be displayed in setting group 1.

- •Set FRAP is ON in setting group 2 for using ramp function.
- •Set the rising time and falling time at -RPU mode and -RPJ mode of setting group 1.
- •Ramp function will be operating when changing the set value at stable control status or supply the power again after the power was removed.
- •The setting range of rising and falling time is 1 to 99 minute.

※ 「用PU function(Delay of rising time)



It makes delay rising temperature when change the set value at stable control status or delay the initial rising temperature as like above picture.

Note) *- RPU* time cannot be shorter than rising time

(tu) of temperature when Ramp function is not used.

※ ► APd function(Delay of falling time)



It controls falling temperature as like above.

Note), AP_d time cannot be shorter than falling time (td) of temperature when Ramp function is not used.

◎ Input correction(ⁱ ∩ ⁻ ^b) function

Input correction is to correct deviation occurred from temperature sensor such as thermocouples, RTD, Analog sensor etc. If you check the deviation of every temperature sensor precisely, it can measure temperature accurately.

- •Input revise can be set at "In-b" mode in setting group 1.
- •Use this mode after measuring deviation occurred from temperature sensor exactly. Because if measured deviation value is not corrected,
- displayed temperature may be too high or too low.
- Setting range of input revise is -49 to 50°C(-50.0 to 50.0°C)
- •When you set the Input revise value, you may need to record it, because it will be useful when performing maintenance.

O Analog input(A-1, A-2, A-3 mode)

•In case of measuring or controlling humidity & pressure, flux, etc, it uses the proper converter which is converting the measuring value to DC4-20mA or 1-5VDC or 0-10VDC.



- •In order to use the analog output of the converter as the controller input, select the input sensor, voltage/current converter switch built in the controller to be a same condition with analog output.(This should be operated in power-off status.)
- •This unit has the mode for the converter built-in. Please select R- !(0-10VDC) or R-2(1-5VDC) or R-3(DC4-20mA) in selection mode of input in setting group 2.
- •Set the input value by High scale (H 5L) and Low scale (L 5L) mode.
- •Please connect the analog output of the converter to the temperature sensor terminal of the controller. Please be cautious of the polarity.
- •After the procedure, it is controlled same with temperature control.
- •Example of usage



Output connections

For more information about output, refer to the H-151 page.

•Application of relay output type



Relay contact terminal Magnet or Keep power relay as far away as power way as power relay as far away as power relay may flow on a coil of magnet switch & power relay may flow in power line of the unit, it may cause malfunction. If wires length of **A** is short, please connect a mylar condenser 104(630V) across coil of the power relay "" to protect electromotive force.

•Application of SSR output type



- SSR should be selected by the capacity of load, otherwise, it may short-circuit and result in a fire. Indirect heated should be used with SSR for efficient working.
- %Please use a cooling plate or it may cause the capability deterioration, breakdown of SSR for a long usage.

•Application of current output(DC4-20mA)



- %It is important to select SCR unit after checking the capacity of the load.
- $\%\ensuremath{\mathsf{If}}$ the capacity is exceeded, it may cause a fire.

•Application of transmission output(DC4-20mA)



•Application of communication output(RS485)



(D) Proximity sensor (E) Pressure sensor (F) Rotary encoder (G) Connector/ Socket (H) Temp, controller (I) SSR/ Power controller (J) Counter (L) Panel meter (M)

Tacho/ Speed/ Pulse

. meter

(N) Display unit

(O) Sensor controller

(P) Switching

(Q) Stepping

(R) Graphic/

Logic panel

(S) Field

network device

(T) Software

(U) Other

motor& Driver&Controlle

power supply

(A) Photo

electric sensor

(B) Fiber

> (C) Door/Area sensor

optic

Communication output

Interface

Standard	EIA RS485
Number of connections	Max. 31units. It is available to set address 01 to 99.
Communication method	2 wire half duplex
Synchronous method	Asynchronous type
Communication distance	Within 1.2km
Communication speed	2400, 4800, 9600(Available to set)
Start bit	1bit(Fixed)
Stop bit	1bit(Fixed)
Parity bit	None
Data bit	8bit(Fixed)
Protocol	BCC

O System ordering



 \times Use a proper twist pair for communication.

Ocommunication control ordering

- 1. The communication control ordering of TZ/TZN series is exclusive protocol.
- 2. After 4sec. being supplied the power into master system, then able to start communicating.
- 3. Initial communication will be started by master system. When Command signal comes out from master system then TZ/TZN series will respond.



Format of Command and Response



①Start code

It indicates the first of Block STX \rightarrow [02H], in case of response, ACK will be added.

②Address code

This code is master system can discern TZ/TZN series and able to set within range of 01 to 99.(BCD ASCII)

③Header code :

- It indicates command as 2 alphabets as below.
- $RX(Read request) \rightarrow R[52H], X[58H]$
- $RD(Read response) \rightarrow R[52H], D[44H]$
- WX(Write request) \rightarrow W[57H], R[58H] WD(Write response) \rightarrow W[57H], D[44H]
- (a) Text : It indicates the detail contents of Command/ Response. (See command)
- (\oplus END code : It indicates the end of Block. ETX \rightarrow [03H]
- ⑥BCC : It indicates XOR operating value from the first to ETX of the protocol as abbreviation of TZ/TZN.

© Communication Command

- •Read[RX] of measurement/setting value :
- Address 01, Command RX
- 1.Command(Master)
 - ①Command

STX	0	1	R	Х	Р	0	ETX	FSC
Start	Addre	SS	Comma head	and	P:Process V S:Setting va	alue	End	BCC

②Application : Address(01), Header code(RX), Process value(P)

STX	0	1	R	Х	Р	0	ETX	FSC
02	30	31	52	58	50	30	03	BCC

•Write[WX] of setting value : Address 01, Command WX 1.Command(Master)

()Command

s	тх	0	1	W	х	s	0	Symbol	10 ³	10 ²	10 ¹	10 [°]	ETX	FSC
s	start	Addr	ess	Comm head	and	S:Set valu	ting Ie	Space/-	10 ³	10²	10 ¹	10º	End	BCC

②Application : In case of writing Address(01), Heading Coad(WX), Setting value(S) +123.

STX	0	1	W	х	s	0	Symbol	10 ³	10 ²	10 ¹	10º	ETX	FSC
02	30	31	57	58	53	30	20	30	31	32	33	03	BCC

Response Response

•Read of process/Setting value

1. In case of receiving normal process value : The data is transmitted adding ACK[60H]. (In case process value is +123.4)

A C K	S T X	0	1	R	D	Р	0	Symbol	10 ³	10 ²	10 ¹	10º	Decimal point	E T X	F S C	N U L L
A C K	S T X	0	1	R	D	Р	0	Space	1	2	3	4	1	E T X	B C C	N U L L
06	02	30	31	52	44	50	30	20	31	32	33	34	31	03	B C C	00

2. In case process value is -100

A C K	S T X	0	1	R	D	Р	0	-	0	1	0	0	0	E T X	B C C	N U L L
06	02	30	31	52	44	50	30	2D	30	31	30	30	30	03	B C C	00

%It is responded with 1 byte sized NULL(00H) at the end of response frame (next BCC 16).

Write of setting value

In case setting value is -100

A C K	S T X	0	1	w	D	s	0	Symbol	10 ³	10²	10 ¹	10º	E T X	F S C
A C K	S T X	0	1	w	D	s	0	-	0	1	0	0	E T X	B C C
06	02	30	31	57	44	53	30	2D	30	31	30	30	03	B C C

•Others : In case of no response of ACK

(1) When the address is not the same after receiving STX.

(2) When receiving buffer overflow is occurred.(3) When the baud rate or others communication setting value are not the same.

•When there are no ACK response ①Check the status of lines

②Check the communication condition(Setting value)③When assuming the problem is due to noise, try to

 operate communication 3 times more until recovery.
 When occurred communication failure frequently, please adjust the communicating speed.

Proper usage

◎ Simple "error" diagnosis

•In case, the load (Heater etc.) is not operated, please check operation of the out lamp located in front panel of the unit. If lamp does not operate, please check the parameter of all programmed mode. If lamp is operating, please check the output (Relay, Driving voltage of SSR, DC4-20mA current) after separating output line from the unit.

But, the out lamp is not operated for DC4-20mA current output.

- •When it displays **_PE** during operation.
 - This is a warning that external sensor is cut off.

Turn off the power of controller and check the error of sensor.

If sensor is not cut off, disconnect sensor line from terminal block and +, - together. When you turn on power it can check room temperature.

If this unit cannot indicate room temperature, this unit itself is faulty. Please remove this unit from equipment and service or replace.

(When the input mode is thermocouple, it is available to indicate room temperature.)

•In case of indicating "Error" in display

This Error message is indicated in case of damaging inner chip program data by outer strong noise.

In this case, please send the unit to our after service center after removing the unit from system.

Noise protection is designed in this unit, but it does not stand up strong noise continuously.

If bigger noise than specified(Max. 2kV) flows in the unit, it can be damaged.

O Caution for using

- •Please use the terminal(M3.5, Max. 7.2mm) when connecting the AC power source.
- ▲ mark indicated on the diagram of this unit means caution-refer to accompanying documents.
- •In case of cleaning the unit, please keep as following Cautions ;

①Clean dust with a dry tissue.

②Be sure to use alcohol to clean the unit, do not use acid, chromic acid, solvent, etc.

③Be sure to clean the unit after turning off the power and then turn on the power after passing 30minute after cleaning.

- •If this unit is used in a manner not to be specified by the manufacture, it can be injury to a person or damage to property.
- •Be sure that metal dust and wire-dregs do not flow in the unit, because of malfunction damage of the unit or the cause of a fire.
- •Service life for the relay of the unit is indicated in this manual, life cycle is different according to the load capacity and switching times, therfore please use the unit after checking the load capacity and switching times.
- •Connect wires correctly after checking polarity of terminals.
- •Do not use this unit as following place.
- A place where dust, corrosive gas, oil, moisture are occurred.

②A place where there are high humidity or freezing place.

③A place where sunshine, radiant heat is occurred.④A place where vibration, shock is occurred.

- •If the equipment is used in a manner not specified by the manufacture the protection provided by the equipment may be impaired.
- •Please install power switch or circuit-breaker in order to cut power supply off.

•A switch or circuit-breaker meeting the relevant requirements of IEC947-1 and IEC947-3 shall be included in equipment when the temperature controller.

- •The switch or circuit-breaker should be installed near by users.
- •Do not use this product as Volt-meter or Amperemeter, this is a temperature controller.
- Installation environment
 It shall be used indoor
 Altitude Max. 2000m
 Pollution Degree 2
 Installation CategoryII.
- •If you want to change the input sensor, reset switches (SW1, SW2) according to each input specification after powe off. Turn on power and then set sensor mode by front keys at second flow chart.

This SSR and current of this controller are insulate from internal power.

•Do not connect power line to sensor connecting part. The inner circuit may be damaged. Example 1
 Example 2
 Example 2

(A) Photo

electric sensor

(B) Fiber

(C) Door/Area sensor

optic

(D) Proximity sensor

(E) Pressure

sensor

(F) Rotary encoder

(G)

Socket

(H) Temp. controlle

> SR/ Sower controller

(J) Counter

nector/

(P) Switching power supply (Q) Stepping

motor& Driver&Controller

(R) Graphic/

Logic panel

(S) Field

network device

(T) Software

(U) Other