# **Small and Amplifier Built-in type**

Side sensing type

BYS500-TDT

## Small emitter/receiver synchronizing type

#### Features

Specifications

Model

Sensing type Sensing distance

Sensing target Response time

Power supply Current consumption

Light source

Operation mode

Control output

Indicator

Vibration

Shock

Environ-

Protection

Accessory

Unit weight

Material

Cable

ment

Protection circuit

Noise resistance

Dielectric strength

Ambient illumination

Ambient temperature

Ambient humidity

Insulation resistance

- Small size: W12×H16×D30mm
- Minimizing malfunction by extraneous light by synchronizing emitter and receiver
- Reverse power polarity and overcurrent protection cicuit

Standard type

Through-beam

Opaque materials of Min. ø5mm

12-24VDC ±10%(Ripple P-P: Max. 10%)

Reverse polarity protection, output short-circuit protection

500m/s2(50G) in each of X, Y, Z directions for 3 times

Sunlight: Max. 11,0001x Incandescent lamp: Max. 3,000 lx

±240V the square wave noise(pulse width: 1μs) by the noise simulator

BY500-TDT

500mm

Max. 30mA

Dark ON

Infrared LED(940nm)

NPN open collector output

Operation indicator: Red LED

Min. 20MΩ(at 500VDC megger)

1,000VAC 50/60Hz for 1minute

-10 to 60°C, storage : -25 to 70°C

Case: ABS, Sensing part: Acrylic

Mounting bracket, Bolts/Nuts

IP50(IEC standard)

Approx. 150g

35 to 85%RH, storage: 35 to 85%RH

• Fast response speed : Max. 1ms

Please read "Caution for your safety" in operation manual before using.



(D) Proximity sensor

(E) Pressure

(H) Temp. controller

(J) Counter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(P) Switching power supply

motor& Driver&Controller

(R) Graphic/

network device

(T) Software

(U) Other

A-25

X The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

**Autonics** 

ø4mm, 4-wire, Length: 2m (Emitter of through-beam type: ø4mm, 3-wire, Length: 2m)

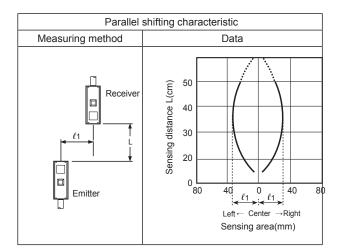
(AWG22, Core diameter: 0.08mm, Nunber of cores: 60, Insulator out diameter: ø1.25mm)

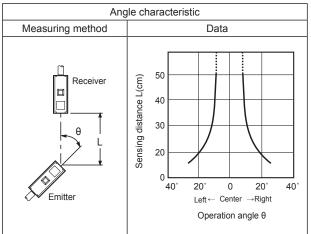
• Load voltage : 30VDC • Load current : Max. 100mA • Residual voltage : Max. 1V

1.5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours

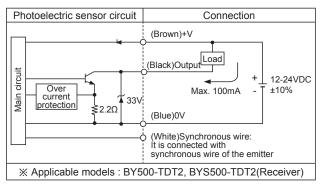
## **BY Serie**

#### ■ Feature data





## **■** Control output diagram

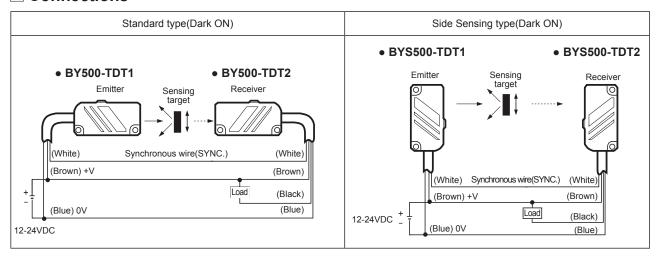


## Operation mode

Operation mode		Dark ON
Receiver operation	Received light	
	Interrupted light	
Operation indicator (red LED)	ON	
	OFF	
Transistor output	ON	
	OFF	

- \* If the control output terminal is short-circuited or overcurrent condition exists, the control otuput turns OFF due to protection circuit.
- × Please supply the power to the brown and the blue wires of the emitter and Synchronous wire(white) of the receiver must be connected with that of the emitter.

### Connections



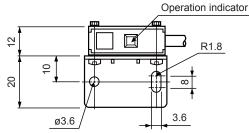
- X The power of the emitter and the receiver must be supplied from same power line.
- X Synchronous wire(white) of the receiver must be connected with that of the emitter, or it may cause malfunction.

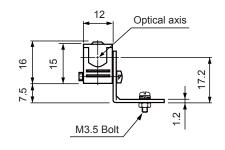
A-26

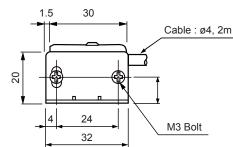
# **Small and Amplifier Built-in type**

■ Dimensions (unit: mm)

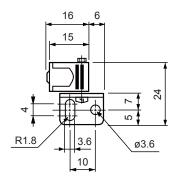


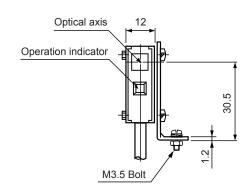


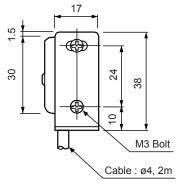




#### • BYS500-TDT

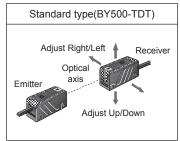


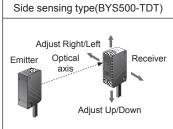




## ■ Mounting and sensitivity adjustment

- 1. Supply the power to the sensor, after installing the emitter and the receiver facing each other.
- 2. Set the receiver in the middle of position where the operation indicator turns ON adjusting the receiver to the right and the left or up and down.
- 3. Fix both units tightly after checking that the unit detects the target.
- ※If a sensing target is translucent body or smaller than ø5mm, it might not be detected because the target allows too much light to pass.





(A) Photo electric

(B) Fiber optic

(C) Door/Area

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary

(G) Connector/ Socket

(H) Temp. controller

> (I) SSR/ Power

(J) Counter

(K)

Panel meter

Tacho/ Speed/ Pulse meter

(N) Display unit

Sensor controller

(P) Switching power supply

(Q) Stepping motor& Driver&Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Software

(U) Other

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